ENGINEERING KNOWLEDGE TEST (EKT) ELECTRICAL AND ELECTRONICS STREAM

Set No 1/15 Booklet Series 'J'

Instructions	for Ca	andidates
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Time Allotted: 45 Minutes

1. 2. 3. 4.	One No m	No. of Ques mark will be ark will be d ot write on th	deduct educte	ed for every d for un-atte	wrong mpted	g answer. I questions.			
Q1.	If x=a	n(cos t + t sin		sin t — t cos t) sin t	. The \ (c)	value of $\frac{dy}{dx}$ itan t		sec ² t	
Q2.	The	area of three cm ³ . The leng 15 cm	e faces	of a cuboic ne shortest ec	d are		2:3:4		ume is
Q3.	$\int \frac{dx}{x \log x}$	$\frac{1}{x}$ is equal to	, ,				, ,		
	(a)	log x+x+c	(b)	log(logx)+c	(c)	xlogx+c	(d)	$\frac{\log x}{x}$ +C	
Q4.		ts numbered probability th		-					
	(a)	8/2	(b)	9/20	(c)	8/15	(d)	2/20	
Q5.	The p	projection of a	vector	on another v	ector is	3			
Q6.	(a) (c) In Mk	Scalar neither vect (S system, we			(b)	Vector either scal	ar or ve	ctor	
Q7.	(c) Wher	mass in kilo time in seco the separati	nd	ween two cha	(b) (d) arges i	distance ir all of these s made four	Э	the force b	etween
	them (a) (c)	increases fo			(b) (d)	decreases			
Q8.	` '	n a conductor			` '				This is
	(a) (c)	Joule's law Coulomb's l	aw		(b) (d)	Faraday's Ampere's			
Q9.	X-rav	s are used fo	r the stu	udv of crystal	structu	ıre because			

- (a)
- X-rays are completely absorbed by the crystal the wavelength of X-ray is of the same order of magnitude in the inter-atomic (b) spacing in crystals
- the wavelength of X-rays is very small in comparison with the inter-atomic spacing in crystals
- the crystals are completely transparent to X-rays (d)

Q10.		ioactive isoto was its origin 600 g					ays. If today 1250 g	y there a (d)	re 125 g of it let 2000 g	t,
Q11.	Angle	s project tru	` ,	J	n the	` '	J		ngle and plane	of
	projec (a)	tion are Aligned	(b)	Adjacent		(c)	Perpendi	cular (d)	Parallel	
Q12.	Tesla is a measure of (a) magnetic flux density (c) magnetic potential						(b) electric flux density(d) electric potential			
Q13.	Admit (a)	tance is recip susceptance				(c) r	eactance	(d)	conductance	
Q14.	(a)	is an ac		er otch filter		(c) B	utterworth fi	ilter (d)	band pass filter	
Q15.	For tra (a) (c)	ansmission li Balun double stub	ne load	matching	ove	r a ra (b) (d)	•	d direction	is best to use a enal coupler	
Q16.	Emitte (a) (c)	er follower is reducing the impedance	gain			(b)	increasing none of th	_	ortion	
Q17.	Binary (a)	/ equivalent o (11101) ₂	` '	o is (11110) ₂		(c)	(101101)2	₂ (d)	(110101) ₂	
Q18.	In Coi (a)	mputer memo 1000	ory size (b)	K indicate 1024	es Ki	ilo, wi (c)	nich is equa 100	l to (d)	10000	
Q19.		table multivib stable state			ate	(c) th	nree stable s	states (d)	two stable states	S
Q20.	An ideal Op Amp has (a) infinite input and output impedance (b) very low input and output impedance (c) low input impedance and very high output impedance (d) infinite input impedance and zero output impedance 									
Q21.	An ins (a) (c)	struction used data transfe logical instru	r instru	•	lag i	in a c (b) (d)	omputer car arithmetic program o	instructi	on	
Q22.	An FE (a) (c)	T is a bipolar sem non semico				(b)	unipolar s both (a) a		uctor device	
Q23.	For G (a) S	unn diodes, s silicon (b)	semico Germai		ateria (c)	-	ferred is ium Arsenid	e (d)	all of these	
Q24.	In a J	FET drain cu	rrent is	maximum	whe	en V _G	_S i s			
	(a) z	ero (b)	nega	tive	(c)	posi	ive	(d)	equal to Vp	

Q25.	The c	output of Lase	r is						
	(a)	Infrared	(b)	polarised	(c)	narrow bea	m (d)	coherent	
Q26.	As compared to a closed loop system an open loop system is (a) more stable as well as more accurate (b) less stable as well as less accurate (c) more stable but less accurate (d) less stable but more accurate								
Q27.	Transfer function of a system is used to calculate (a) the steady state gain (b) the time constant (c) the order of the system (d) the output for a given input								
Q28.	In a c (a) (b) (c) (d)	output signa	n depe al is fed y is bet	ystem ends upon the I back to be co tter than in the	ompare	ed with the ref			
Q29.				rence input a trolling signal		•	•	is called ransfer function	
Q30.	If the (a)	transfer funct	ion of a	a system is $\frac{1}{\mathrm{Ts}+}$		steady state e nfinite		unit step input is none of these	
Q31.	In a F	PID controller	the va	lues of propor	tional,	integral and	derivati	ve are dependent	
	 (a) future, past and present errors respectively (b) present, past and future errors respectively (c) past, present and future errors respectively (d) present, future and past errors respectively 								
Q32.		nverse Laplac						04	
	(a)	2(t+1)	(b)	2e ^{-t}	(c)	2e ^t	(d)	e ^{-2t}	
Q33.	The s require (a)	-	ded fro	om 96KHz to 1	(c)	z, so the mini	mum sa (d)	ampling frequency	
Q34.	A diffe (a) (c)	erentiation cir very high tin infinite time	ne con	stant	(b) (d)	very low tim			
Q35.	Ideally Voltage Standing Wave Ratio (VSWR) should be (a) as large as possible (b) as small as possible (c) as close to unity as possible (d) infinity								
Q36.	Follov (a) (c)	wing is/are a p it is an nonli it maps a lai values to a s	near pi	t of input	f quant (b) (d)	tization it is an irrev all of these	ersible	process	

Q37.	Most commonly used filter in SSB generation are (a) mechanical filters (b) RC filters (c) LC filters (d) low pass filters
Q38.	If the antenna diameter in a radar system is increased by a factor of 4, the maximum range will be increased by a factor of (a) 2 (b) 4 (c) 8 (d) 16
Q39.	Following type of multiplexing cannot be used for analog signalling (a) FDM (b) TDM (c) CDM (d) None of these
Q40.	In TDM systems, channel separation is done with the use of (a) AND gates (b) band-pass filters (c) differentiator circuit (d) integrator circuit
Q41.	Data-link layer of the OSI model specifies (a) data link procedures that provide for the exchange of data via frames that can be sent and received (b) the interface between the X.25 network and packet mode device (c) the virtual circuit interface to packet-switched service (d) all of the above
Q42.	FDDI is a (a) ring network (b) star network (c) mesh network (d) bus based network
Q43.	Which of the following TCP/IP protocol allows an application program on one machine to send a datagram to an application program on another machine? (a) UDP (b) VMTP (c) X.25 (d) SMTP
Q44.	The main difference between synchronous and asynchronous transmission is that (a) the clocking is derived from the data in synchronous transmission (b) the clocking is mixed with the data in asynchronous transmission (c) the pulse height is different (d) the bandwidth required is different
Q45.	Transducer is a device which (a) converts one form of power in to the other (b) is similar to transformer (c) converts one form of energy in to other (d) helps in measuring electricity
Q46.	Principle of hysteresis is not used in (a) electrical water geyser (b) electrical motor (c) multi-vibrators (d) Schmitt trigger
Q47.	Which of the following motors would not be suitable for use as servomotors? (a) AC induction motor (b) brushless AC motor (c) stepper motor (d) permanent magnet DC motor
Q48.	The stator of an induction motor is made of (a) carbon (b) wood (c) copper stampings (d) silicon steel laminators
Q49.	An ideal DC generator is one that has voltage regulation (a) low (b) high (c) zero (d) positive
Q50.	Commutator is used in (a) DC generator (b) AC generator (c) invertors (d) convertors